

Direct Georeferencing and Control System for Small Aircraft



- Programmable sensor trigger
- Designed for small unmanned aircraft, based on the most accurate GNSS/IMU system in its category:
 APX-15 El from Applanix.
- Onboard powerful microcontroller allows telemetry and camera control through the drone's payload channel.
- → Dual sensor control: camera + LiDAR, etc.
- ★ External secundary IMU for gimballed cameras
- Power and control signals for two sensors
- → Optional long range direct radio link





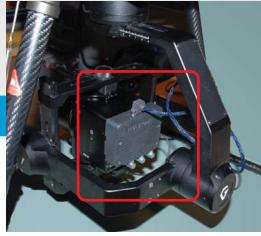
All the interfaces needed for any kind of sensor payload





Specifications (*)

- Autopilot interface: 2x serial ports 3.3V
- Camera / LIDAR Interface:
 - Serial port RS232 level
 - PPS output 5V
 - Trigger signal 5V
- IMU / Camera Interface:
 - External IMU port for gimbaled camera
 - RS232 serial port
 - Camera trigger output signal 5V
 - Camera ready input signal 5V
 - Camera power
- Power input/output 9 36 VDC
 - Power output polarity protected.
- USB interface for mission controller
- Ethernet interface for APX15 configuration and data download.
- Optional long range radio link



External IMU adapter specially designed for Phase One cameras.

With the built-in powerful microprocessor inside the G2-DGX150, you have an intelligent mission control system capable of a fully autonomous and efficient data acquisition. It allows you to:

- Use the drone's autopilot payload data channels to monitor and remote control the sensor(s) on board.
- Manage up to two sensors (i.e. Camera and Lidar)
- Upload a mission plan with predetermined photocenters, or trigger parameters to ensure photo overlap.
- Send corrections to the autopilot if it derives from the planned track (autopilot type dependent functionality)

We can do customized payload and drone integrations. Please contact us to discuss your specific requirements.